

Domain Specific Languages for Small Embedded Systems

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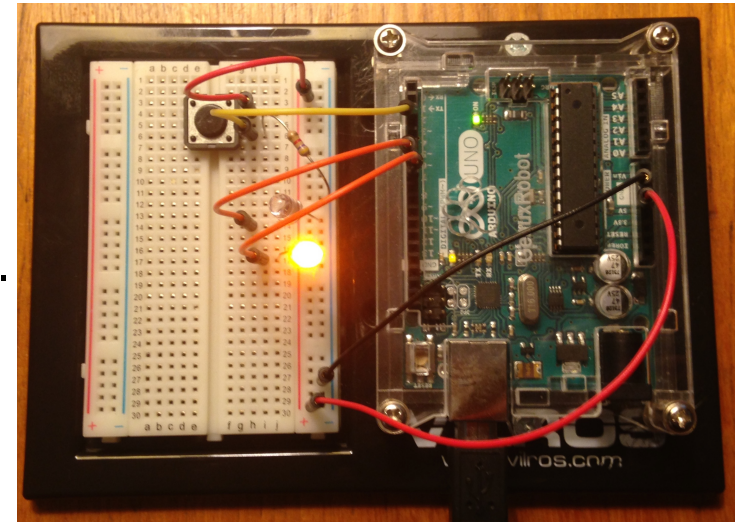
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Small Embedded Systems

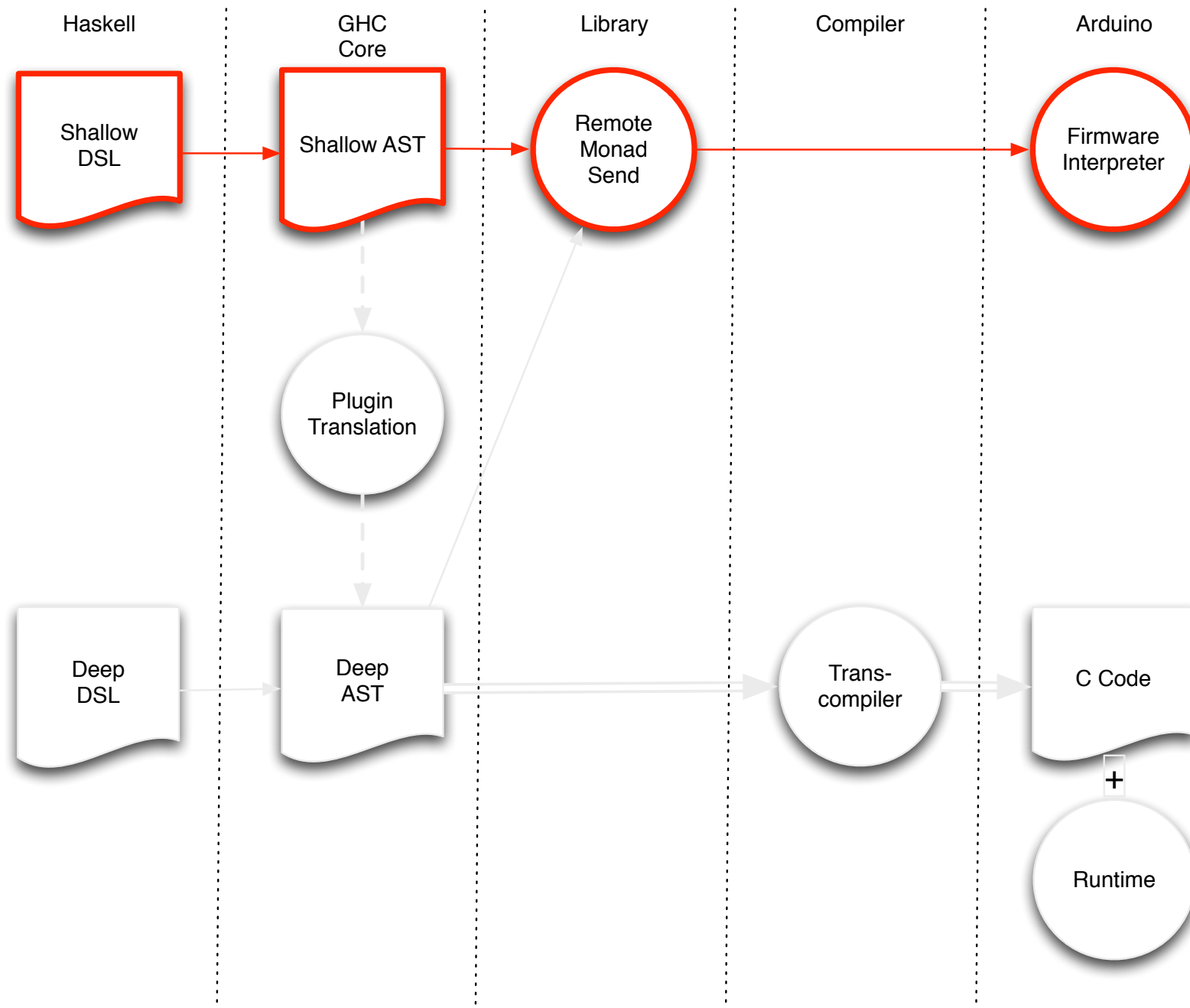
- Small, resource constrained embedded systems provide a challenge to programming with high level functional languages.
- Their small RAM and permanent storage resources make it impossible to run Haskell directly on them.
- Embedded Domain Specific Languages (EDSL) provides an alternative.
- Using an EDSL a user is able to write in a high level, functional host language.
- Execution can be through either interpretation or compilation.



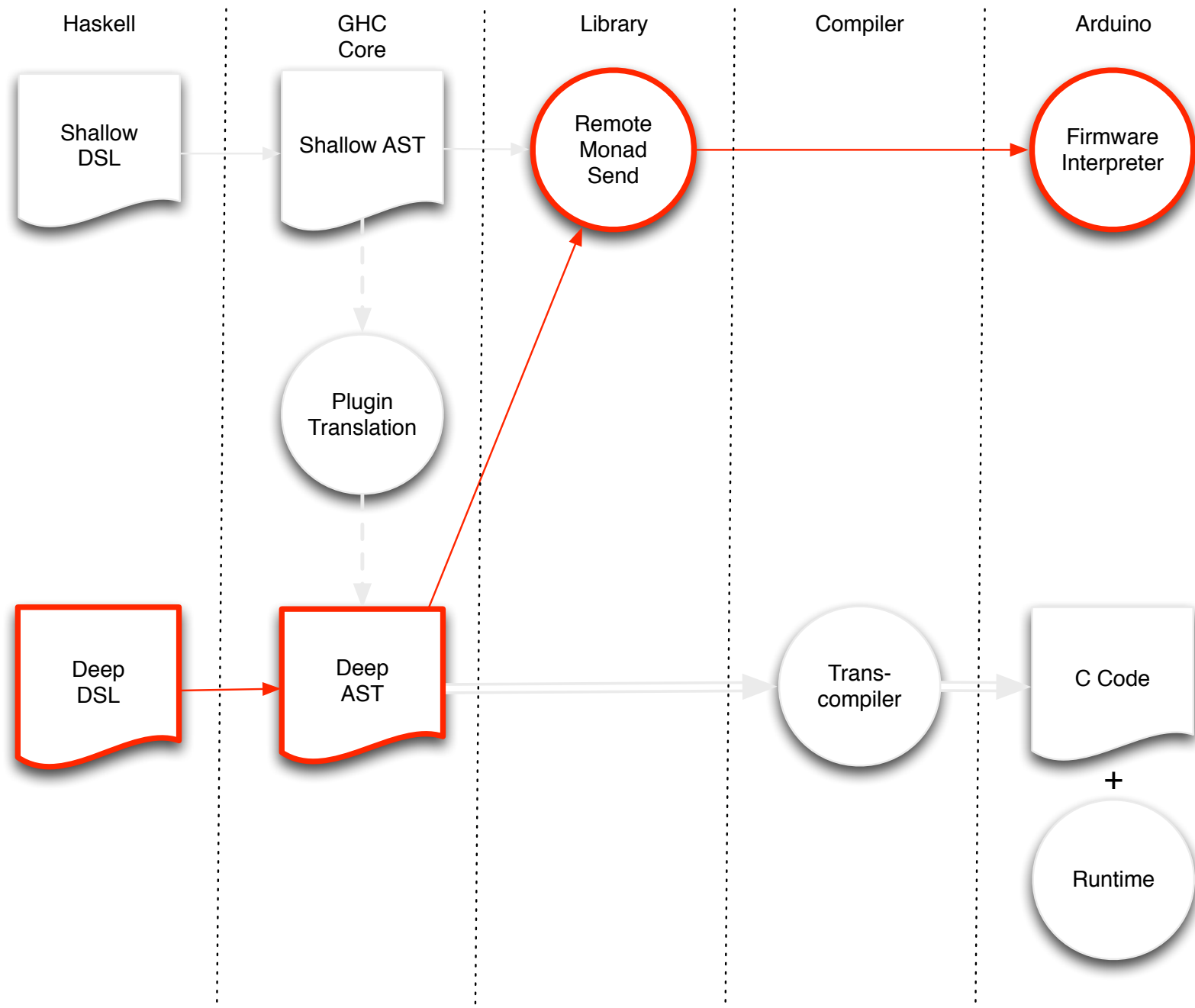
Embedded Domain Specific Languages

| | Interpretation/Remote Execution | Code Generation/Compilation |
|---------------------|---|--|
| Shallow EDSL | <i>Examples</i> Blank Canvas hArduino Haxl <i>Advantages</i> Ease of development Quick turnaround | <i>Examples</i> Haskino <i>Advantages</i> Ease of development Performance Resource Optimization |
| Deep EDSL | <i>Advantages</i> Debugging | <i>Examples</i> Kansas Lava Feldspar Ivory <i>Advantages</i> Performance Resource Optimization |

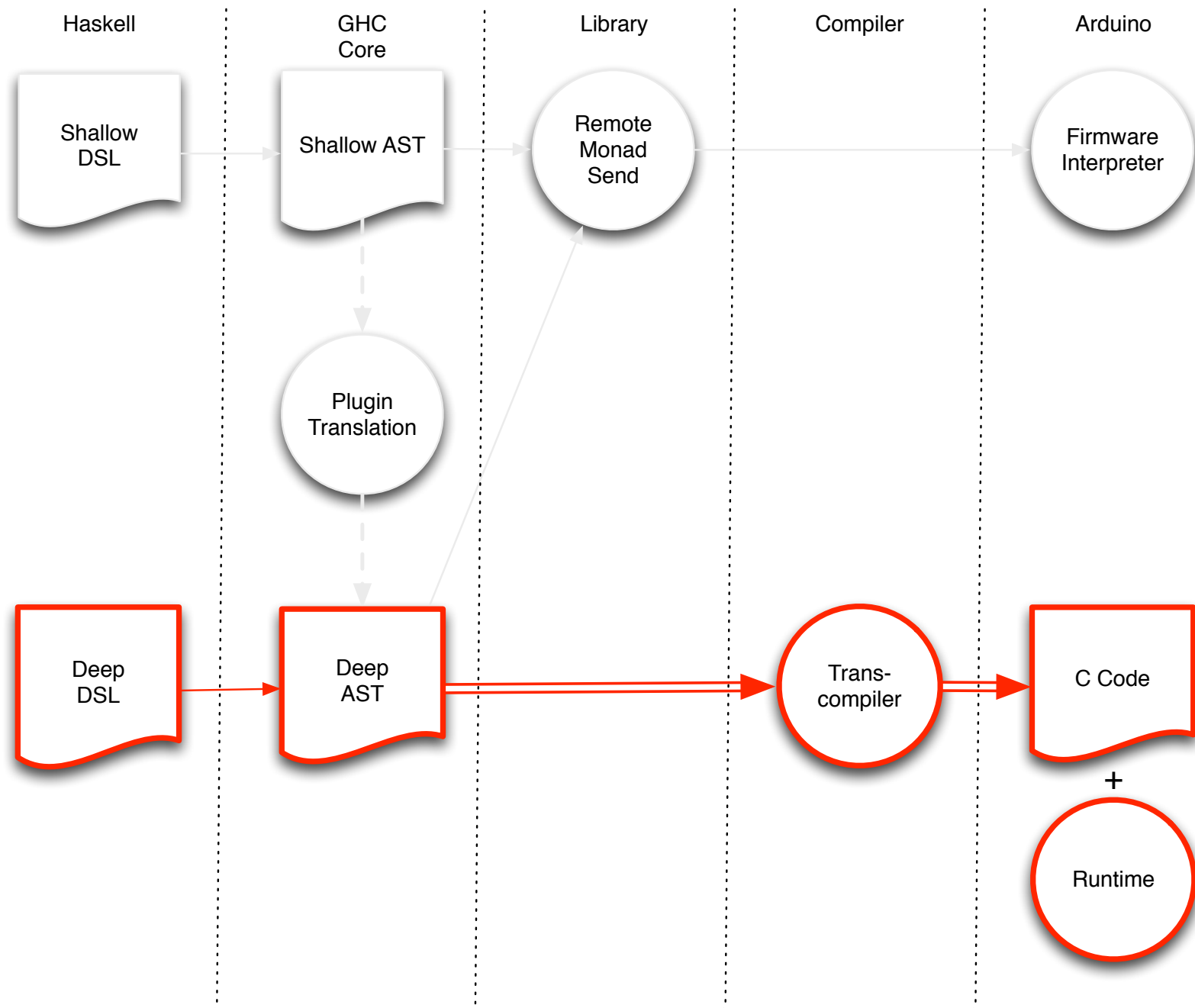
Haskino Overview



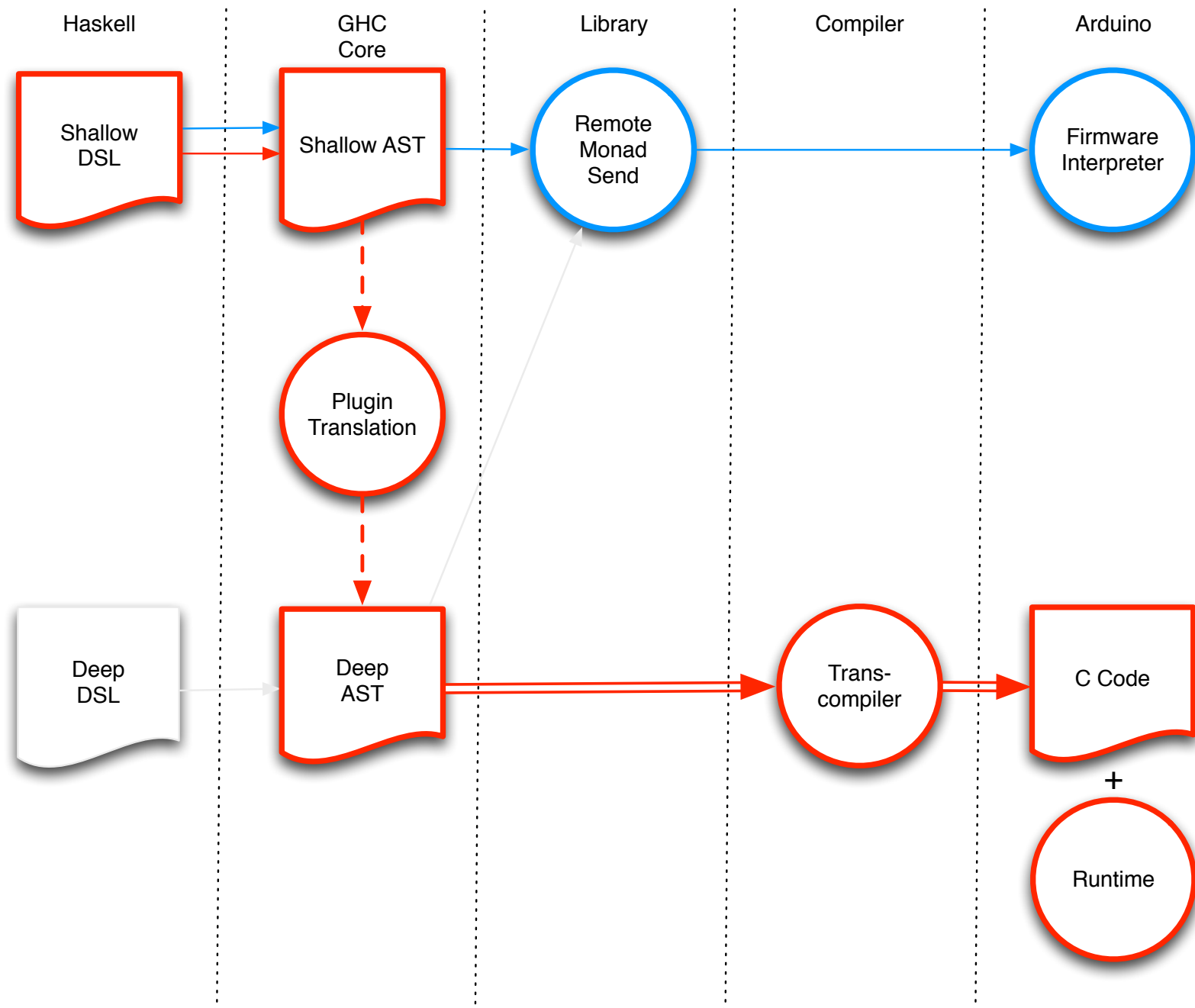
Haskino Overview



Haskino Overview



Haskino Overview



Remote Monads

A remote **command** is a request to perform an action for remote effect, where there is no result value

```
digitalWrite :: Word8 -> Bool -> Arduino ()  
send         :: ArduinoConnection -> Arduino a -> IO a
```

```
GHCi> send conn $ digitalWrite 2 True  
Arduino: LED on pin 2 turns on
```

A remote **procedure** is a request to perform an action for its remote effects, where there is a result value or temporal consequence

```
digitalRead :: Word8-> Arduino Bool
```

```
GHCi> send conn $ digitalRead 3  
Arduino: Returns the state of Pin 3
```


Shallow Haskino example

- To demonstrate shallow Haskino syntax, I will use a simple Haskino example.
- The example consists of two buttons and a LED and will light the LED if either button is pressed.
- The shallow version of the example is:

```
program :: Arduino ()
program = do
  let button1 = 2
      button2 = 3
      led = 13
  loop do
    a <- digitalRead button1
    b <- digitalRead button2
    digitalWrite led (a || b)
    delayMillis 100
```

Deep: Adding Expressions

The tethered shallow Haskino uses commands and procedures such as:

```
digitalWrite :: Word8 -> Bool -> Arduino ()  
analogRead   :: Word8 -> Arduino Word16
```

To move to the deeply embedded version, we instead use:

```
digitalWriteE :: Expr Word8 -> Expr Bool ->  
              Arduino (Expr ())  
analogReadE   :: Expr Word8 ->  
              Arduino (Expr Word16)
```

Expression Types

The Haskino EDSL provides **Expr** a parameterized over the following types, which are instances of the **ExprB** typeclass:

- **Word8**
- **Word16**
- **Word32**
- **Int8**
- **Int16**
- **Int32**
- **Bool**
- **Float**
- **[Word8]**

- Numeric operations include addition, subtraction, division, multiplications, comparisons, and conversion between numeric types.
- Boolean operations include **not**, **and**, and **or**. Integer operations include standard bitwise operations.
- **[Word8]** operations include append and element retrieval.
- Values are lifted into the **Expr** type by the **lit** function.

Conditionals

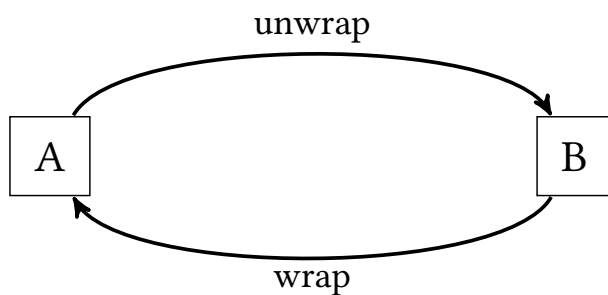
Conditionals become another data structure constructor when we move to the deep DSL:

```
button <- digitalRead 2
if button
  then digitalWrite 2 True
  else digitalWrite 3 True
```

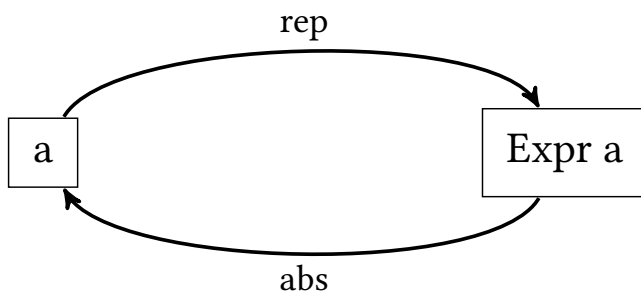
```
button <- digitalReadE (lit 2)
ifThenElseE button (digitalWriteE (lit 2) (lit True))
               (digitalWriteE (lit 3) (lit True))
```

Transformations

Worker-Wrapper



- In general, these take a function $f = body$
- And apply transforms such that $f = wrap\ work$
 $work = unwrap\ body$
- Moving between the A and B types.



- In our specific case, we move between a and $Expr\ a$
- rep is the equivalent of lit , and abs corresponds to evaluation of the Expr.

Shallow/Deep Translation

- Using worker-wrapper based transformations, the shallow DSL can be changed to the deep DSL.
- We automate this using a GHC plugin to do transformations in Core to Core passes.

```
loop do
  a <- digitalRead button1
  b <- digitalRead button2
  digitalWrite led (a || b))
  delayMillis 100
```



```
loopE do
  a' <- digitalReadE (rep button1)
  b' <- digitalReadE (rep button2)
  digitalWriteE (rep led) ( a' ||* b' )))
  delayMillisE (rep 100))
```

Translate the Primitives

Insert worker-wrapper ops by translating primitives of the form:

a1 -> ... -> an -> Arduino b

to ones of the form:

Expr a1 -> ... -> Expr an -> Arduino (Expr b)

```
loop (  
  digitalRead button1 >>=  
  (\a -> digitalRead button2 >>=  
    (\b -> digitalWrite led (a || b))) >>  
  delayMillis 100)
```



```
loopE (  
  abs <$> digitalReadE (rep button1) >>=  
  (\ a -> abs <$> digitalReadE (rep button2) >>=  
    (\ b -> digitalWriteE (rep led) (rep (a || b)))) >>  
  delayMillisE (rep 1000))
```


Transform Operations

Translate the shallow operations to deep Expr operations:

$rep (x \text{ `shallowOp` } y)$ transforms to $(rep x) \text{ `deepOp` } (rep y)$

where the types of shallowOp and deepOp are:

$shallowOp :: a \rightarrow b \rightarrow c$ and $deepOp :: Expr a \rightarrow Expr b \rightarrow Expr C$

```
loopE (  
  abs <$> digitalReadE (rep button1) >>=  
    (\ a -> abs <$> digitalReadE (rep button2) >>=  
      (\ b -> digitalWriteE (rep led) (rep (a || b)))) >>  
      delayMillisE (rep 1000))
```



```
loopE (  
  abs <$> digitalReadE (rep button1) >>=  
    (\ a -> abs <$> digitalReadE (rep button2) >>=  
      (\ b -> digitalWriteE (rep led) ((rep a) ||* (rep b)))) >>  
      delayMillisE (rep 1000))
```

Move Abs Through Binds

Move the abs operations through the monadic binds

$$(abs \langle \$ \rangle f) \gg = k$$

making it a composition of the continuation with the abs:

$$f \gg = k . abs$$

```
loopE (  
  abs <$> digitalReadE (rep button1) >>=  
    (\ a -> abs <$> digitalReadE (rep button2) >>=  
      (\ b -> digitalWriteE (rep led) ((rep a) ||* (rep b)))) >>  
      delayMillisE (rep 1000))
```



```
loopE (  
  digitalReadE (rep button1) >>=  
    (\ a -> digitalReadE (rep button2) >>=  
      (\ b -> digitalWriteE (rep led) ((rep a) ||* (rep b))) . abs  
    ) . abs >>  
    delayMillisE (rep 1000))
```

Move the abs inside the Lambdas

Move the abs operations inside the Lambdas

$(\lambda x \rightarrow f[x]) . abs$

by changing the parameter of the lambda to have the abs applied.

$(\lambda x' \rightarrow let\ x=abs\ x'\ in\ f[x])$

```
loopE (  
  digitalReadE (rep button1) >>=  
    (\ a -> digitalReadE (rep button2) >>=  
      (\ b -> digitalWriteE (rep led) ((rep a) ||* (rep b))) .  
abs) . abs >>  
    delayMillisE (rep 1000))
```



```
loopE (  
  digitalReadE (rep button1) >>=  
    (\ a' -> digitalReadE (rep button2) >>=  
      (\ b' -> digitalWriteE (rep led) ((rep (abs a')) ||* (rep  
abs b'))))) >>  
    delayMillisE (rep 1000))
```

Fuse Rep/Abs

Finally, with the abs moved into position, we are able to fuse the rep and the abs:

rep (abs a) becomes *a*

```
loopE (  
  digitalReadE (rep button1) >>=  
    (\ a' -> digitalReadE (rep button2) >>=  
      (\ b' -> digitalWriteE (rep led) ((rep (abs a')) ||* (rep  
(abs b'))))) >>  
    delayMillisE (rep 1000))
```



```
loopE (  
  digitalReadE (rep button1) >>=  
    (\ a' -> digitalReadE (rep button2) >>=  
      (\ b' -> digitalWriteE (rep led) (a' ||* b'))) >>  
    delayMillisE (rep 1000))
```

Conditional Transformation

Conditionals are handled similarly to the primitive transformations:

```
forall (b :: Bool) (m1 :: ExprB a => Arduino a)
                    (m2 :: ExprB a => Arduino a).
if b then m1 else m2
  =
abs <$> ifThenElseE (rep b) (rep <$> m1)
                    (rep <$> m2)
```

```
forall (b :: Bool) (t :: ExprB a => a)
                    (e :: ExprB a => a).
if b then t else e
  =
abs $ ifB (rep b) (rep t) (rep e)
```

Recursion vs Iteration

- The Haskino EDSL includes an iteration primitive...

```
iterateE :: Expr a ->
          (Expr a -> Arduino (ExprEither a b)) ->
          Arduino (Expr b)
```

- However, we would like to write in a recursive style, as opposed to an iterative imperative style as follows:

```
led = 13
button1 = 2
button2 = 3

blink :: Word8 -> Arduino ()
blink 0 = return ()
blink t = do
    digitalWrite led True
    delayMillis 1000
    digitalWrite led False
    delayMillis 1000
    blink $ t-1
```

Deep Recursion

```
blinkeE :: Expr Word8 -> Arduino (Expr ())
blinkeE t =
  ifThenElseE (t ==* rep 0)
    (return (rep ()))
    (do digitalWriteE (rep led) (rep True)
        delayMillisE (rep 1000)
        digitalWriteE (rep led) (rep False)
        delayMillisE (rep 1000)
        blinkeE (t - (rep 1)))
```



```
blinkeE :: Expr Word8 -> Arduino (Expr ())
blinkeE t =
  iterateE t $ do
    ifThenElseEither (t ==* rep 0)
      (return (ExprRight (rep ())))
      (do digitalWriteE (rep led) (rep True)
          delayMillisE (rep 1000)
          digitalWriteE (rep led) (rep False)
          delayMillisE (rep 1000)
          return (ExprLeft (t - (rep 1))))
```

Shallow/Deep + Recursion Translation

```
analogKey :: Arduino Word8
analogKey = do
  v <- analogRead button2
  case v of
    _ | v < 30  -> return KeyRight
    _ | v < 150 -> return KeyUp
    _ | v < 350 -> return KeyDown
    _ | v < 535 -> return KeyLeft
    _ | v < 760 -> return KeySelect
    _           -> analogKey
```

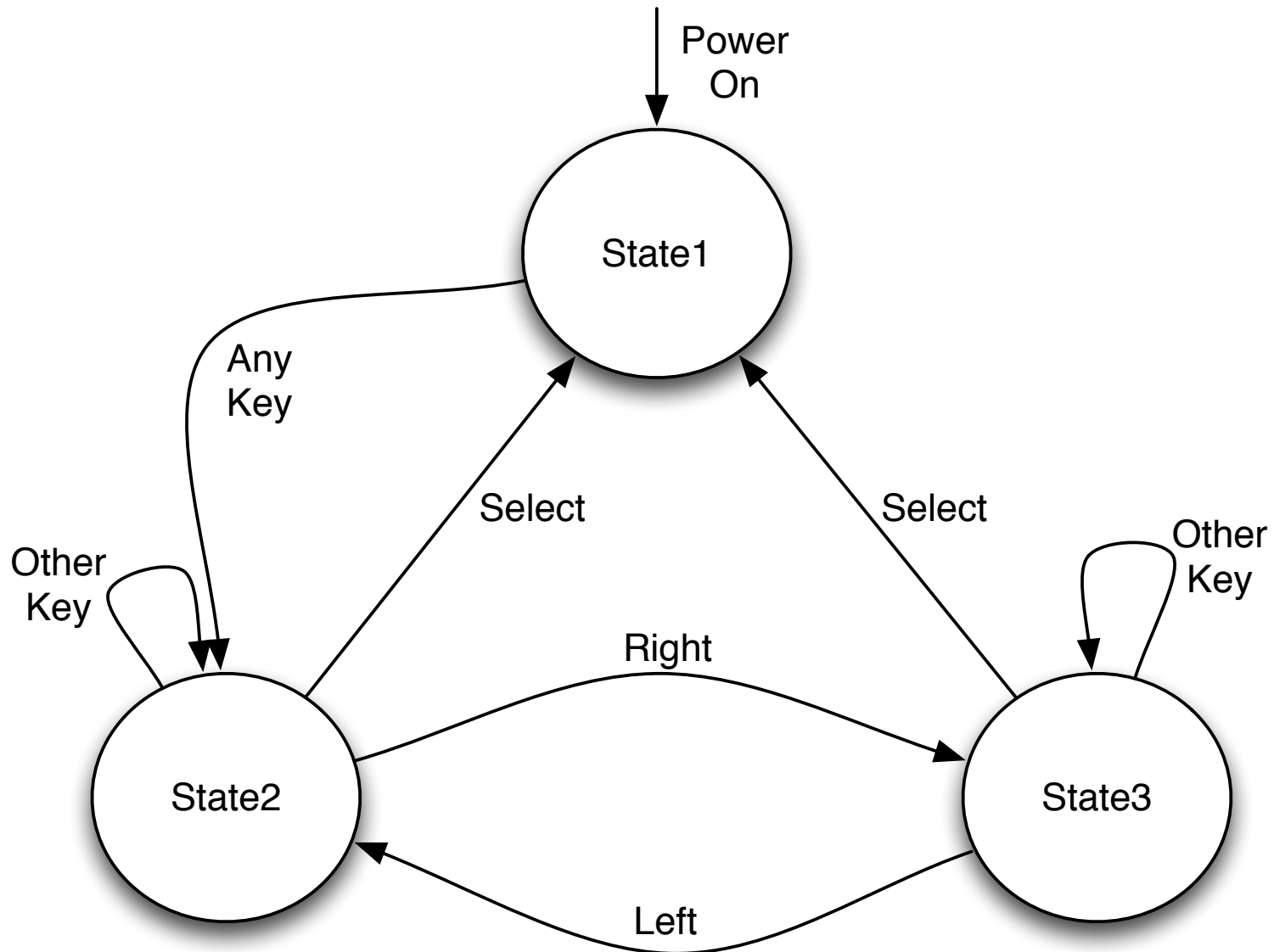


```
analogKeyE :: Arduino (Expr Word8)
analogKeyE = analogKeyE' (lit ())

analogKeyE' :: Expr () -> Arduino (Expr Word8)
analogKeyE' t = iterateE t analogKeyE'I

analogKeyE'I :: Expr () ->
  Arduino (ExprEither () Word8)
analogKeyE'I _ = do
  v <- analogReadE button2
  ifThenElseEither (v <* 30)
    (return (ExprRight (lit KeyRight)))
    (ifThenElseEither (v <* 150)
      (return (ExprRight (lit KeyUp)))
      (ifThenElseEither (v <* 350)
        (return (ExprRight (lit KeyDown)))
        (ifThenElseEither (v <* 535)
          (return (ExprRight (lit KeyLeft)))
          (ifThenElseEither (v <* 760)
            (return (ExprRight (lit KeySelect)))
            (return (ExprLeft (lit ())))))))))
```


Mutual Recursion



Mutual Recursion

```
stateMachine :: LCD -> Arduino ()
stateMachine lcd = state1 $ keyValue KeyNone
  where
    state1 :: Word8 -> Arduino ()
    state1 k = do
      displayState lcd 1 k
      key <- analogKey
      case key of
        _ -> state2 key
```

```
state2 :: Word8 -> Arduino ()
state2 k = do
  displayState lcd 2 k
  key <- analogKey
  case key of
    1 -> state3 key
    5 -> state1 key
    _ -> state2 key
state3 :: Word8 -> Arduino ()
state3 k = do
  displayState lcd 3 k
  key <- analogKey
  case key of
    2 -> state2 key
    5 -> state1 key
    _ -> state3 ke
```

Mutual Recursion

```
stateMachine_deep :: LCD -> Arduino (Expr ())
stateMachine_deep lcd = state1_deep (lit (keyValue KeyNone))
  where
    state1_deep :: Expr Word8 -> Arduino (Expr ())
    state1_deep k = state1_deep_mut (lit 0) k

    state2_deep :: Expr Word8 -> Arduino (Expr ())
    state2_deep k = state1_deep_mut (lit 1) k

    state3_deep :: Expr Word8 -> Arduino (Expr ())
    state3_deep k = state1_deep_mut (lit 2) k

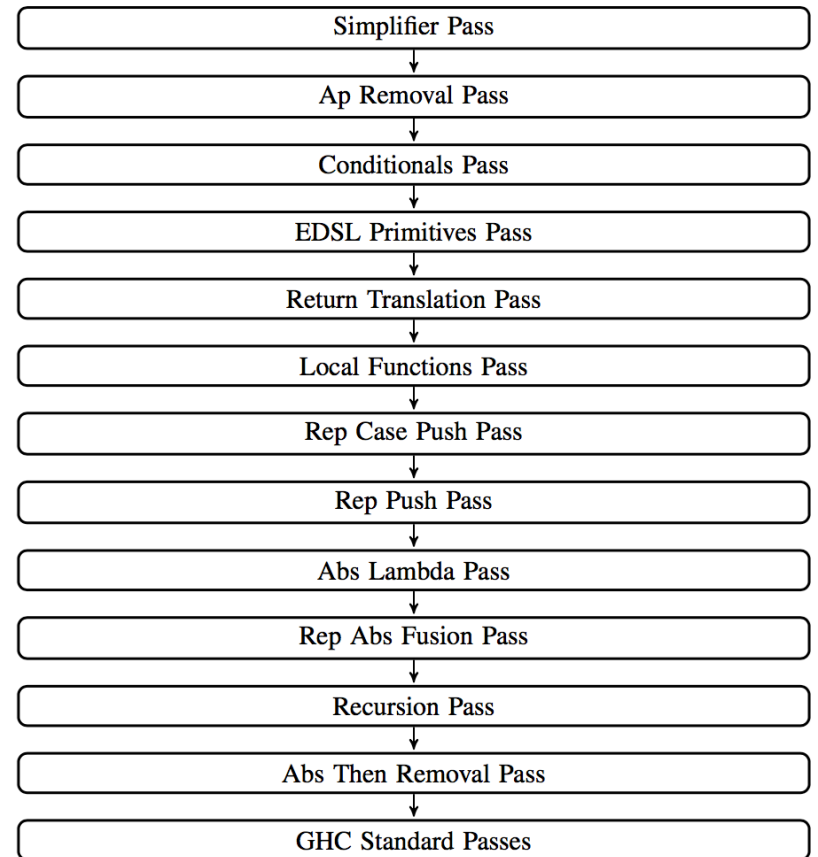
    state1_deep_mut :: Expr Int -> Expr Word8 -> Arduino (Expr ())
    state1_deep_mut = iterateE i k state1_deep_mut_step
```

Mutual Recursion

```
state1_deep_mut_step :: Expr Int -> Expr Word8 -> Arduino (ExprEither Word8 ())
state1_deep_mut_step i k =
  ifThenElseEither (i ==* (lit 0))
    (transformed state 1 deep code)
    (ifThenElseEither (i ==* (lit 1))
      (transformed state 2 deep code)
      (transformed state 3 deep code))
```

GHC Plugins

- GHC's compiler plugin architecture allows the compiler user to modify or add passes to the compiler's optimizer phase.



```
type Plugin =  
  [CommandLineOption] -> [Pass] -> CoreM [Pass]
```

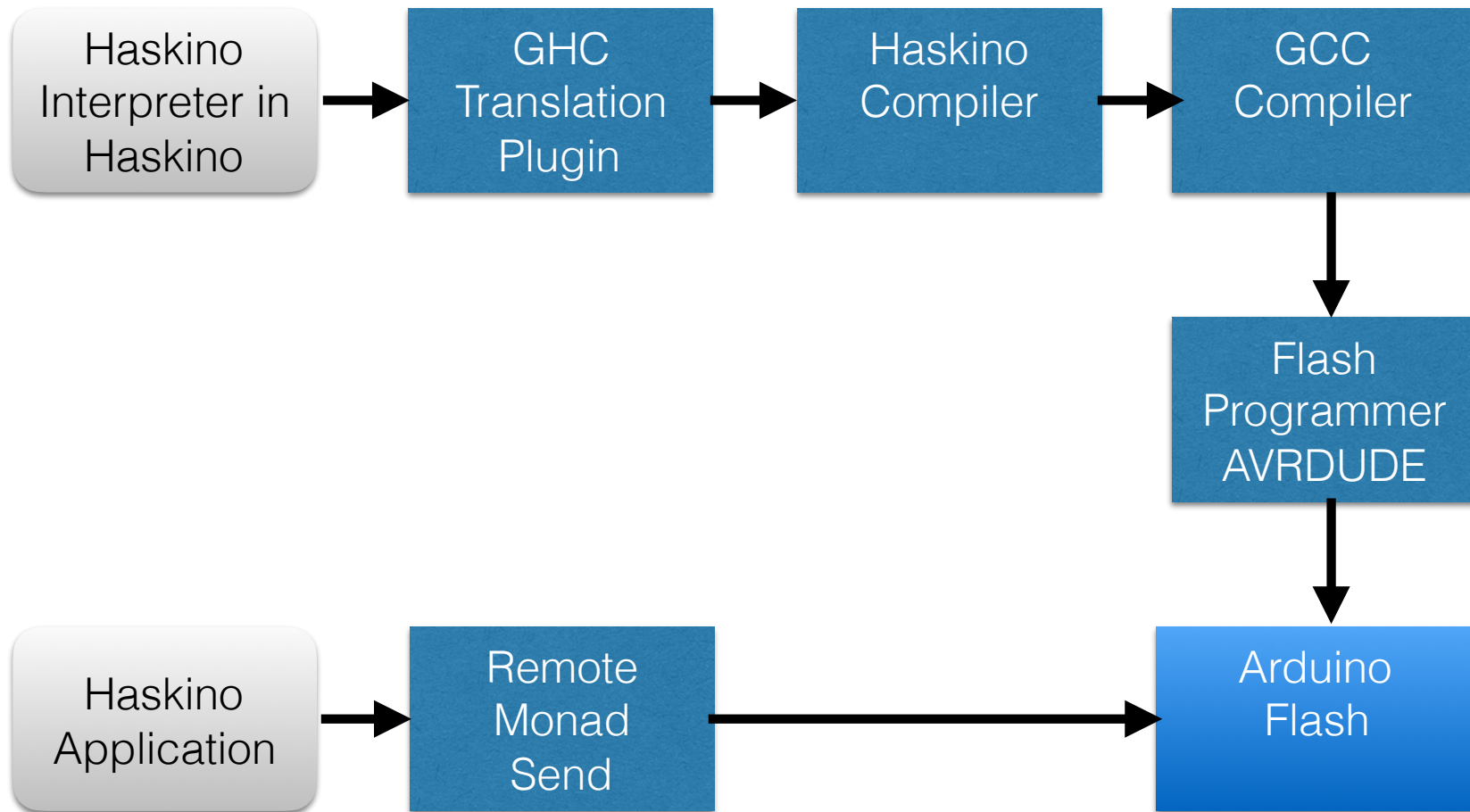
- Each pass is a Core to Core transformation.

```
type Pass = ModGuts -> CoreM ModGuts
```

Limitations

- Recursion Transformation only works on functions of zero or one arguments.
 - Addition of tuples to EDSL would remove limit.
- Three known untranslatable syntax constructs
 - `| ++ [c]` (ironically due to **build** construct)
 - Enum typeclass (limits on `fromEnum`)
 - `modifyRemoteRef` (translation of lambda function parameters)
 - These may be addressed by additions to the transformation logic/EDSL, and currently all have workarounds.

Haskino Bootstrap



Interpreter Resource Usage

Flash Usage

| | Shallow Haskino Interpreter in C | Shallow Haskino Interpreter in Haskino | |
|--------------------------|---|---|-------------|
| Arduino Libraries | 1032 bytes | 1032 bytes | |
| Haskino Runtime | - | 3602 bytes | |
| Applications | 11396 bytes | 18384 bytes | +61% |
| Total Flash | 12428 bytes | 23018 bytes | +85% |

Ram Usage

| | Shallow Haskino Interpreter in C | Shallow Haskino Interpreter in Haskino | |
|-------------------------|---|---|-------------|
| Scheduler | - | 84 bytes | |
| Message Buffers | 32 bytes | 96 bytes | |
| Apps/Libs | 502 bytes | 561 bytes | +12% |
| Total Static Ram | 534 bytes | 742 bytes | +39% |
| Total Stack Ram | 51 bytes | 50 bytes | 0% |

Interpreter Performance

| | Shallow Haskino Interpreter in C | Shallow Haskino Interpreter in Haskino | |
|--------------------------------|---|---|--------------|
| Processing digitalRead | 4.168 ms | 4.093 ms | -1.8% |
| Communication Time | 1.042 ms | 1.042 ms | |
| Host Time | 0.133 ms | 0.133 ms | |
| Processing digitalWrite | 8.204 ms | 8.222 ms | +0.2% |
| Communication Time | 6.163 ms | 6.163 ms | |
| Host Time | 0.188 ms | 0.188 ms | |

Code Sharing

- Some Deep Functions are “staged” by the plugin such that the Haskino Compiler is able to transform them into C functions as opposed to inlined code.

```
exampleFunc :: Expr Int -> Expr Int -> Arduino(Expr Int)
exampleFunc x y = return $ x + y
```



```
exampleFunc :: Expr Int -> Expr Int -> Arduino(Expr Int)
exampleFunc x y =
    app2Arg "exampleFunc" (exprArgType x) (exprArgType y)
        (exprRetType (exampleFunc_orig (remArg 0) (remArg 1)))

exampleFunc_orig :: Expr Int -> Expr Int -> Arduino(Expr Int)
exampleFunc_orig x y = return $ x + y
```

Flash Usage After Optimization

| | Shallow Haskino Interpreter in C | Shallow Haskino Interpreter in Haskino | |
|--------------------------|---|---|-------------|
| Arduino Libraries | 1032 bytes | 1032 bytes | |
| Haskino Runtime | - | 3602 bytes | |
| Applications | 11396 bytes | 12744 bytes | +12% |
| Total Flash | 12428 bytes | 17378 bytes | +40% |

Future Work

- Implement Sharing Optimization
- Extend Translation to Higher Order Transversal functions.
- Generalization to non-monadic EDSLs

Publications

Accepted

- M. Grebe and A. Gill. Haskino: A Remote Monad for Programming the Arduino. In Practical Aspects of Declarative Languages, Springer (2016) 153-168
- M. Grebe and A. Gill. Threading the Arduino with Haskell. In Trends In Functional Programming, Springer 2017 (In Press)
- M. Grebe, D. Young, and A. Gill, “Rewriting a shallow dsl using a ghc compiler extension,” in Proceedings of the 16th ACM SIGPLAN International Conference on Generative Programming: Concepts and Experiences, ser. GPCE 2017, New York, NY, USA: ACM, 2017, pp. 246–258.
- A. Gill, N. Sculthorpe, J. Dawson, A. Eskilson, A. Farmer, M. Grebe, J. Rosenbluth, R. Scott, J. Stanton. The remote monad design pattern. In Proceedings of the 8th ACM SIGPLAN Symposium on Haskell, pages 59–70. ACM, 2015.
- J. Dawson, M. Grebe, and A. Gill, “Composable network stacks and remote monads,” in Proceedings of the 10th ACM SIGPLAN International Symposium on Haskell, ser. Haskell 2017. New York, NY, USA: ACM, 2017, pp. 86–97.

Submitted

- M. Grebe, D. Young, and A. Gill, “Rewriting a shallow dsl using a ghc compiler extension,” extended version submitted to Computer Languages, Systems & Structures, Elsevier 2018

Conclusion

- One set of shallow source....
- Passed through a transformation plugin which is customizable for many EDSLs....
- Produces an language system with both ease of use, quick turnaround, and good performance.

Thank you for your attention

github.com/ku-fpg/haskino

<http://ku-fpg.github.io/people/markgrebe/>